

## Description

The 9DB436 is a zero delay/fanout buffer for PCI Express™ clocking. It supports PCIe Gen1–3 in zero delay mode and PCIe Gen1–4 in fanout mode. The 9DB436 is a pin-compatible upgrade to the 9DB433 and 9DB434 with a Safe-Power-Sequence (SPS) clock input.

## Typical Applications

- Riser cards
- Storage
- Networking
- JBOD

## Output Features

- Four 0.7V current-mode differential HCSL output pairs
- Supports zero delay buffer (ZDB) mode and fanout mode
- Selectable bandwidth for zero delay mode
- 50–110 MHz operation in PLL mode
- 5–166 MHz operation in Bypass mode

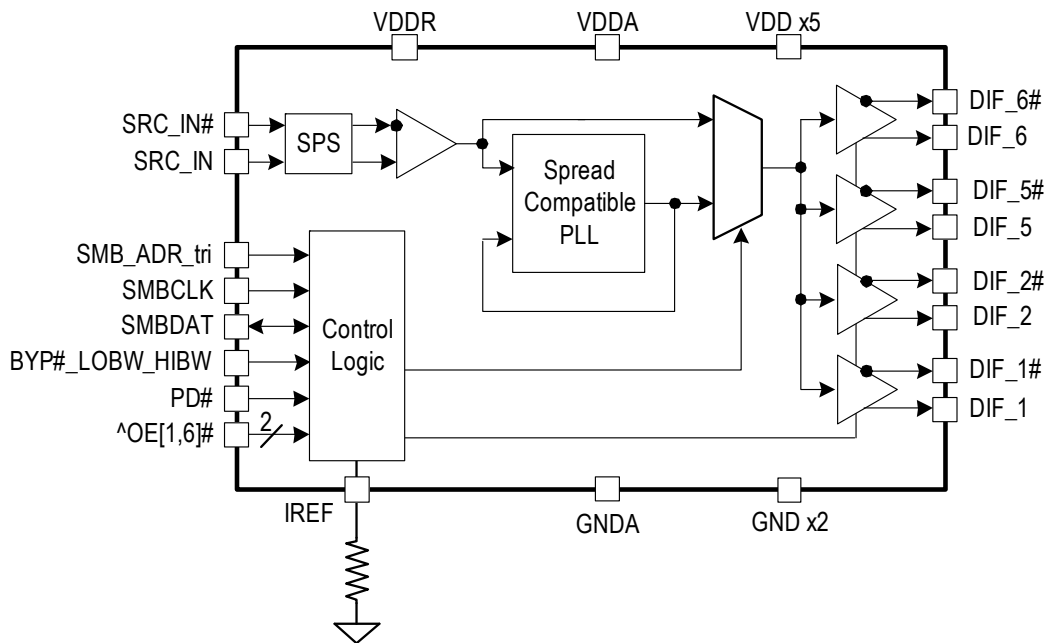
## Features

- SPS internal receiver bias network keeps input clock parked when input is floating
- Supports both 85Ω and 100Ω output impedance with appropriate resistor selection
- OE# pins default to controlling outputs
- PLL or Bypass mode; PLL can dejitter incoming clock
- Selectable PLL bandwidth; minimizes jitter peaking in downstream PLLs
- Spread spectrum compatible
- Outputs default to Hi-Z when disabled or when device is powered down
- SMBus interface; unused outputs can be disabled
- 3 selectable SMBus addresses

## Key Specifications

- PCIe Gen3 jitter < 0.6ps rms in ZDB mode
- PCIe Gen4 additive jitter < 0.1ps rms in fanout mode
- Output cycle-to-cycle jitter < 50ps
- Output-to-output skew < 50ps

## Block Diagram



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## Pin Assignments

Figure 1. Pin Assignments for 28TSSOP Package – Top View

VDDR	1	28	VDDA
SRC_IN	2	27	GNDA
SRC_IN#	3	26	IREF
GND	4	25	^PD#
VDD	5	24	VDD
DIF_1	6	23	DIF_6
DIF_1#	7	22	DIF_6#
^OE1#	8	21	^OE6#
DIF_2	9	20	DIF_5
DIF_2#	10	19	DIF_5#
VDD	11	18	VDD
BYP#_HIBW_LOBW	12	17	SMB_ADR_tri
SMBCLK	13	16	VDD
SMBDAT	14	15	GND

v indicates internal pull-down resistor

^ indicates internal pull-up resistor

Pin 12 and pin 17 are latched on power-up. Ensure that the power supply to the pull-up/pull-down resistors ramps at the same time as the main supply to the chip.

## Pin Descriptions

Table 1. Pin Descriptions

Number	Name	Type	Description
1	VDDR	Power	Power supply for differential input clock (receiver). This VDD should be treated as an analog power rail and filtered appropriately. Nominally 3.3V.
2	SRC_IN	Input	HCSL SRC true input.
3	SRC_IN#	Input	HCSL SRC complementary input.
4	GND	GND	Ground pin.
5	VDD	Power	Power supply, nominally 3.3V.
6	DIF_1	Output	HCSL true clock output.
7	DIF_1#	Output	HCSL complementary clock output.
8	^OE1#	Input	Active low input for enabling output 1. This pin has an internal pull-up resistor. 1 = disable output, 0 = enable output.
9	DIF_2	Output	HCSL true clock output.
10	DIF_2#	Output	HCSL complementary clock output.
11	VDD	Power	Power supply, nominally 3.3V.
12	BYP#_HIBW_LOBW	Input	Tri-level input to select bypass mode, Hi BW PLL, or Lo BW PLL mode.
13	SMBCLK	Input	Clock pin of SMBUS circuitry.
14	SMBDAT	I/O	Data pin of SMBUS circuitry.
15	GND	GND	Ground pin.
16	VDD	Power	Power supply, nominally 3.3V.
17	SMB_ADR_tri	Input	SMBus address select bit. This is a tri-level input that decodes 1 of 3 SMBus addresses.

Table 1. Pin Descriptions (Cont.)

Number	Name	Type	Description
18	VDD	Power	Power supply, nominally 3.3V.
19	DIF_5#	Output	HCSL complementary clock output.
20	DIF_5	Output	HCSL true clock output.
21	^OE6#	Input	Active low input for enabling output 6. This pin has an internal pull-up resistor. 1 = disable output, 0 = enable output.
22	DIF_6#	Output	HCSL complementary clock output.
23	DIF_6	Output	HCSL true clock output.
24	VDD	Power	Power supply, nominally 3.3V.
25	^PD#	Input	Asynchronous active low input pin used to power down the device. Normally, the internal clocks are disabled and the VCOs and the XTAL oscillator (if any) are stopped. See the SMBus options for exact behavior. This pin has an internal pull-up resistor.
26	IREF	Output	This pin establishes the reference for the differential current-mode output pairs. It requires a fixed precision resistor to ground. 475Ω is the standard value for 100Ω differential impedance. Other impedances require different values.
27	GNDA	GND	Ground pin for the PLL core.
28	VDDA	Power	Power supply for PLL core.

## Power Connections

Pin Number		Description
V <sub>DD</sub>	GND	
1	4	SRC_IN/SRC_IN#
5,11,18, 24	4	DIF (1, 2, 5, 6)
16	15	Digital VDD/GND
28	27	Analog VDD/GND for PLL and IREF

For best results, also treat pin 1 as analog VDD.

## Operating Mode Readback

BYP#_LOBW_HIBW	Mode	Byte0, bit 3	Byte 0, bit 1
Low	Bypass	0	0
Mid	PLL 100M Hi BW	1	0
High	PLL 100M Low BW	0	1

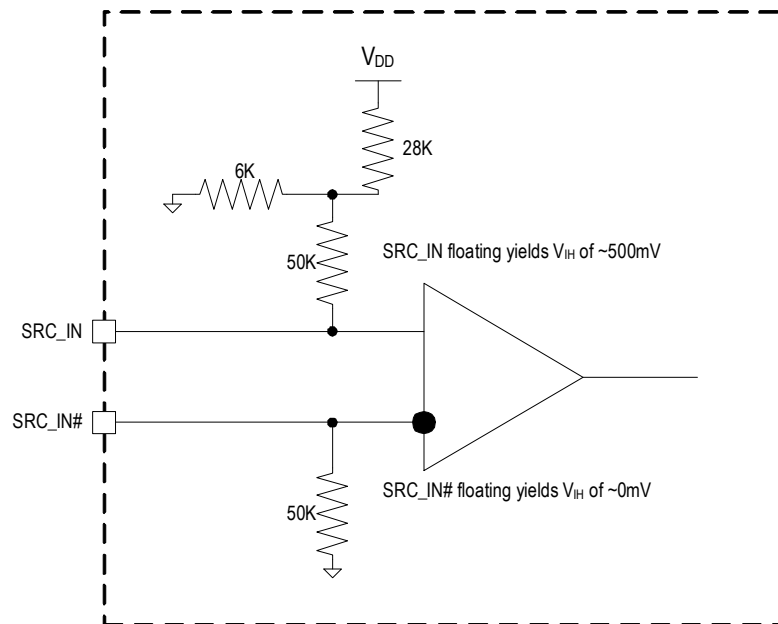
## SMBus Address Selection and Readback

SMB_ADR_tri	Address
Low	DA/DB
Mid	DC/DD
High	D8/D9

## Tri-level Input Logic Levels

State of Pin	Voltage
Low	< 0.8V
Mid	$1.2 < V_{in} < 1.8V$
High	$V_{in} > 2.0V$

Figure 2. Safe Power Sequence (SPS) Clock Input



## Absolute Maximum Ratings

Stresses above the ratings listed below can cause permanent damage to the 9DB436. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

Table 2. Absolute Maximum Ratings

Parameter	Symbol	Conditions	Minimum	Typical	Maximum	Units	Notes
3.3V Core Supply Voltage	$V_{DDA/R}$				4.6	V	1,2
3.3V Core Logic Voltage	$V_{DD}$				4.6	V	1,2
SMBus Supply Voltage	$V_{DDSMB}$	SMBus pull-up resistor voltage.			5.5	V	1
Input Low Voltage	$V_{IL}$		GND-0.5			V	1
Input High Voltage	$V_{IH}$	Except for SMBus interface.			$V_{DD}+0.5$	V	1
Storage Temperature	$T_s$		-65		150	°C	1
Junction Temperature	$T_j$				125	°C	1
Input ESD Protection	ESD prot	Human Body Model.	2000			V	1

<sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup> Operation under these conditions is neither implied nor guaranteed.

## Electrical Characteristics

Table 3. Input/Supply/Common Parameters

 $T_A = T_{IND}$  unless otherwise indicated. Supply voltage  $V_{DD} = 3.3V \pm 5\%$ .

Parameter	Symbol	Conditions	Minimum	Typical	Maximum	Units	Notes
Ambient Operating Temperature	$T_{IND}$	Industrial range.	-40		85	°C	1
Input High Voltage	$V_{IH}$	Single-ended inputs, except SMBus, low threshold and tri-level inputs.	2		$V_{DD} + 0.3$	V	1
Input Low Voltage	$V_{IL}$	Single-ended inputs, except SMBus, low threshold and tri-level inputs.	GND - 0.3		0.8	V	1
Input Current	$I_{IN}$	Single-ended inputs, $V_{IN} = GND$ , $V_{IN} = V_{DD}$ .	-5	-0.02	5	μA	1
	$I_{INP}$	Single-ended inputs. $V_{IN} = 0V$ ; inputs with internal pull-up resistors. $V_{IN} = V_{DD}$ ; inputs with internal pull-down resistors.	-100		100	μA	1
Input Frequency	$F_{ibyp}$	$V_{DD} = 3.3V$ , Bypass Mode.	5		166	MHz	2
	$F_{ipll}$	$V_{DD} = 3.3V$ , 100MHz PLL Mode.	50	100	110	MHz	2
Pin Inductance	$L_{pin}$				7	nH	1
Capacitance	$C_{IN}$	Logic inputs, except DIF_IN.	1.5		5	pF	1
	$C_{INDIF\_IN}$	DIF_IN differential clock inputs.	1.5		2.7	pF	1,4
	$C_{OUT}$	Output pin capacitance.			6	pF	1
Clk Stabilization	$T_{STAB}$	From $V_{DD}$ power-up and after input clock stabilization or deassertion of PD# to 1st clock.			1	ms	1,2
Input SS Modulation Frequency for PCIe	$f_{MODIN}$	Allowable frequency (Triangular modulation).	30	31.5	33	kHz	1
OE# Latency	$t_{LATOE\#}$	DIF start after OE# assertion. DIF stop after OE# deassertion.	1	2	3	cycles	1,3
Tdrive_PD#	$t_{DRVPD}$	DIF output enable after PD# deassertion.		13	300	μs	1,3
Tfall	$t_F$	Fall time of control inputs.			5	ns	1,2
Trise	$t_R$	Rise time of control inputs.			5	ns	1,2

<sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup> Control input must be monotonic from 20% to 80% of input swing.

<sup>3</sup> Time from deassertion until outputs are > 200mV.

<sup>4</sup> DIF\_IN input.

Table 4. SMBus Parameters

 $T_{AMB} = T_{IND}$  unless otherwise indicated. Supply voltage  $V_{DD} = 3.3V \pm 5\%$ .

Parameter	Symbol	Conditions	Minimum	Typical	Maximum	Units	Notes
SMBus Input Low Voltage	$V_{ILSMB}$				0.8	V	1
SMBus Input High Voltage	$V_{IHSMB}$		2.1		$V_{DDSMB}$	V	1
SMBus Output Low Voltage	$V_{OLSMB}$	At $I_{PULLUP}$ .			0.4	V	1
SMBus Sink Current	$I_{PULLUP}$	At $V_{OL}$ .	4			mA	1
Nominal Bus Voltage	$V_{DDSMB}$	3V to 5V $\pm 10\%$ .	2.7		5.5	V	1
SCLK/SDATA Rise Time	$t_{RSMB}$	(Maximum $V_{IL} - 0.15V$ ) to (Minimum $V_{IH} + 0.15V$ ).			1000	ns	1
SCLK/SDATA Fall Time	$t_{FSMB}$	(Minimum $V_{IH} + 0.15V$ ) to (Maximum $V_{IL} - 0.15V$ ).			300	ns	1
SMBus Operating Frequency	$f_{MAXSMB}$	Maximum SMBus operating frequency.			400	kHz	1,5

<sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup> Control input must be monotonic from 20% to 80% of input swing.

<sup>3</sup> Time from deassertion until outputs are  $> 200mV$ .

<sup>4</sup> DIF\_IN input.

<sup>5</sup> The differential input clock must be running for the SMBus to be active.

Table 5. DIF\_IN Clock Input Parameters

 $T_{AMB} = T_{IND}$  unless otherwise indicated. Supply voltage  $V_{DD} = 3.3V \pm 5\%$ .

Parameter	Symbol	Conditions	Minimum	Typical	Maximum	Units	Notes
Input Crossover Voltage	$V_{CROSS}$	Crossover voltage.	150	375	900	mV	1
Input Swing – DIF_IN	$V_{SWING}$	Differential value.	300			mV	1
Input Slew Rate – DIF_IN	$dv/dt$	Measured differentially.	0.6		8	V/ns	1,2
Input Leakage Current	$I_{IN}$	SRC_IN, $V_{IN} = GND$ .			125	$\mu A$	
		SRC_IN#, $V_{IN} = V_{DD}$ .	-100			$\mu A$	
Input Duty Cycle	$d_{tin}$	Measurement from differential waveform.	45	50	55	%	1
Input Jitter – Cycle to Cycle	$J_{DIFIn}$	Differential measurement.	0		125	ps	1

<sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup> Slew rate measured through  $\pm 75mV$  window centered around differential zero.

Table 6. DIF 0.7V Current Mode Differential Outputs

 $T_{AMB} = T_{IND}$  unless otherwise indicated. Supply voltage  $V_{DD} = 3.3V \pm 5\%$ .

Parameter	Symbol	Conditions	Minimum	Typical	Maximum	Units	Notes
Slew Rate	$T_{RF}$	Scope averaging on.	2	2.8	4	V/ns	1,2,3
Slew Rate Matching	$\Delta T_{RF}$	Slew rate matching. Scope averaging on.		8	20	%	1,2,4
Voltage High	$V_{HIGH}$	Statistical measurement on single-ended signal using oscilloscope math function (scope averaging on).	660	797	850	mV	1
Voltage Low	$V_{LOW}$		-150	14	150		1
Maximum Voltage	$V_{max}$	Measurement on single-ended signal using absolute value (scope averaging off).		813	1150		1
Minimum Voltage	$V_{min}$		-300	-1			1
Crossing Voltage (abs)	$V_{cross\_abs}$	Scope averaging off.	250	378	550		1,5
Crossing Voltage (var)	$\Delta V_{cross}$	Scope averaging off.		16	140		1,6

<sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.  $I_{REF} = V_{DD}/(3 \times R_R)$ . For  $R_R = 475\Omega$  (1%),  $I_{REF} = 2.32mA$ .  $I_{OH} = 6 \times I_{REF}$  and  $V_{OH} = 0.7V$  at  $Z_o = 50\Omega$  (100 $\Omega$  differential impedance).

<sup>2</sup> Measured from differential waveform.

<sup>3</sup> Slew rate is measured through the  $V_{swing}$  voltage range centered around differential 0 V. This results in a  $\pm 150mV$  window around differential 0V.

<sup>4</sup> Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a  $\pm 75mV$  window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

<sup>5</sup>  $V_{cross}$  is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

<sup>6</sup> The total variation of all  $V_{cross}$  measurements in any particular system. Note that this is a subset of  $V_{cross\_min/max}$  ( $V_{cross}$  absolute) allowed. The intent is to limit  $V_{cross}$  induced modulation by setting  $\Delta V_{cross}$  to be smaller than  $V_{cross}$  absolute.

Table 7. Current Consumption

 $T_{AMB} = T_{IND}$  unless otherwise indicated. Supply voltage  $V_{DD} = 3.3V \pm 5\%$ .

Parameter	Symbol	Conditions	Minimum	Typical	Maximum	Units	Notes
Operating Supply Current	$I_{DD3.3OP}$	All outputs active at 100MHz, PLL Mode, $C_L =$ full load.		78	103	mA	1
Power Down Current	$I_{DD3.3PD}$	All differential pairs driven.		28	36	mA	1
	$I_{DD3.3PDZ}$	All differential pairs tri-stated.		3	6	mA	1

<sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.



Table 8. Output Duty Cycle, Jitter, Skew and PLL Characteristics

 $T_{AMB} = T_{IND}$  unless otherwise indicated. Supply voltage  $V_{DD} = 3.3V \pm 5\%$ .

Parameter	Symbol	Conditions	Minimum	Typical	Maximum	Units	Notes
PLL Bandwidth	$B_W$	-3dB point in High BW Mode (industrial).	1.5	2.8	4	MHz	1
		-3dB point in High BW Mode (commercial).	2	2.8	4	MHz	1
		-3dB point in Low BW Mode.	0.7	1.1	1.4	MHz	1
PLL Jitter Peaking	$t_{JPEAK}$	Peak pass band gain.		1.5	2	dB	1
Duty Cycle	$t_{DC}$	Measured differentially, PLL Mode.	45	49.2	55	%	1
Duty Cycle Distortion	$t_{DCD}$	Measured differentially, Bypass Mode at 100MHz.	-1	-0.4	1	%	1,4
Skew, Input to Output	$t_{pdBYP}$	Bypass Mode, $V_T = 50\%$ (industrial).	3500	4263	4900	ps	1
		Bypass Mode, $V_T = 50\%$ (commercial).	3500	4115	4500	ps	1
	$t_{pdPLL}$	PLL Mode $V_T = 50\%$ .	-250	-45	250	ps	1
Skew, Output to Output	$t_{sk3}$	$V_T = 50\%$ (industrial).		40	60	ps	1
		$V_T = 50\%$ (commercial).		40	50	ps	1
Jitter, Cycle to Cycle	$t_{jcc-cyc}$	PLL Mode.		21	50	ps	1,3
		Additive jitter in Bypass Mode.		3	10	ps	1,3

<sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup>  $I_{REF} = V_{DD}/(3 \times R_R)$ . For  $R_R = 475\Omega$  (1%),  $I_{REF} = 2.32mA$ .  $I_{OH} = 6 \times I_{REF}$  and  $V_{OH} = 0.7V$  at  $Z_o = 50\Omega$ .

<sup>3</sup> Measured from differential waveform.

<sup>4</sup> Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in Bypass mode.

Table 9. Filtered Phase Jitter Parameters – PCIe Common Clocked (CC) Architectures

 $T_{AMB} = T_{IND}$  unless otherwise indicated. Supply voltage  $V_{DD} = 3.3V \pm 5\%$ .

Parameter	Symbol	Conditions	Minimum	Typical	Maximum	Specification Limit	Units	Notes
Phase Jitter, PLL Mode	$t_{jphPCIeG1-CC}$	PCIe Gen1.		25	35	86	ps (p-p)	1,2,3
	$t_{jphPCIeG2-CC}$	PCIe Gen2 Low Band. 10kHz < f < 1.5MHz		0.74	1.11	3	ps (rms)	1,2
		PCIe Gen2 High Band. 1.5MHz < f < Nyquist (50MHz)		1.95	2.36	3.1	ps (rms)	1,2
	$t_{jphPCIeG3-CC}$	PCIe Gen3. (PLL BW of 2–4MHz or 2–5MHz, CDR = 10MHz).		0.51	0.60	1	ps (rms)	1,2

Table 9. Filtered Phase Jitter Parameters – PCIe Common Clocked (CC) Architectures (Cont.)

 $T_{AMB} = T_{IND}$  unless otherwise indicated. Supply voltage  $V_{DD} = 3.3V \pm 5\%$ .

Parameter	Symbol	Conditions	Minimum	Typical	Maximum	Specification Limit	Units	Notes
Additive Phase Jitter, Bypass Mode	$t_{jphPCIeG1-CC}$	PCIe Gen1.		5.4	8	Not Applicable	ps (p-p)	1,2,3,4
	$t_{jphPCIeG2-CC}$	PCIe Gen2 Low Band. 10kHz < f < 1.5MHz		0.004	0.01		ps (rms)	1,2,3,4,6
		PCIe Gen2 High Band. 1.5MHz < f < Nyquist (50MHz)		0.10	0.13		ps (rms)	1,2,3,4,6
	$t_{jphPCIeG3-CC}$	PCIe Gen3. (PLL BW of 2–4MHz or 2–5MHz, CDR = 10MHz).		0.05	0.06		ps (rms)	1,2,3,4,6
	$t_{jphPCIeG4-CC}$	PCIe Gen4. (PLL BW of 2–4MHz or 2–5MHz, CDR = 10MHz).		0.05	0.06		ps (rms)	1,2,3,4,6

Table 10. Filtered Phase Jitter Parameters – PCIe Independent Reference (IR) Architectures

 $T_{AMB} = T_{IND}$  unless otherwise indicated. Supply voltage  $V_{DD} = 3.3V \pm 5\%$ .

Parameter	Symbol	Conditions	Minimum	Typical	Maximum	Industry Limits	Units	Notes
Additive Phase Jitter, Bypass mode	$t_{jphPCIeG2-SRIS}$	PCIe Gen2. (PLL BW of 16MHz, CDR = 5MHz).		0.12	0.16	Not Applicable	ps (rms)	1,4,5,6,7
	$t_{jphPCIeG3-SRIS}$	PCIe Gen3. (PLL BW of 2–4MHz, CDR = 10MHz).		0.03	0.04		ps (rms)	1,4,5,6,7

**Notes on PCIe Filtered Phase Jitter tables:**

- <sup>1</sup> Applies to all differential outputs, guaranteed by design and characterization.
- <sup>2</sup> Calculated from Intel™-supplied Clock Jitter tool, when driven by Wenzel Associates 100MHz oscillator.
- <sup>3</sup> Sample size of at least 100K cycles. This figure extrapolates to 108ps peak-peak at 1M cycles for a BER of  $10^{-12}$ .
- <sup>4</sup> IR is the new name for Separate Reference Independent Spread (SRIS) and Separate Reference no Spread (SRnS) PCIe clock architectures.
- <sup>5</sup> According to the PCIe Base Specification Rev4.0 version 1.0, the jitter transfer functions and corresponding jitter limits are not defined for the IR clock architecture. Widely accepted industry limits using widely accepted industry filters are used to populate this table. The PCIe Base Specification Rev5.0 is expected to resolve this.
- <sup>6</sup> Additive jitter for RMS values is calculated by solving for b [ $b = \sqrt{c^2 - a^2}$ ] where “a” is rms input jitter and ‘c’ is rms total jitter.

## Test Loads and Terminations

Figure 3. HCSL Differential Output Test Load – Source Terminated

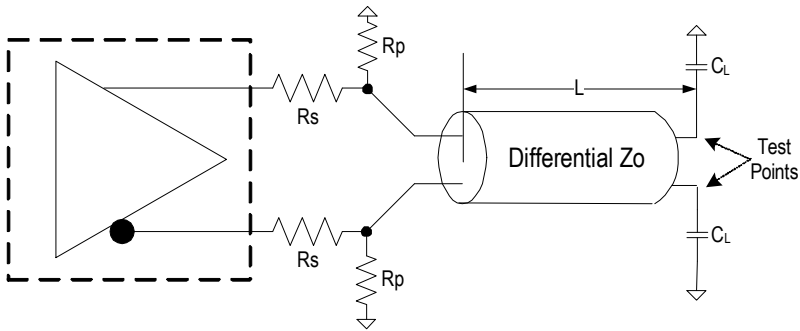


Table 11. Differential Output Termination

DIF ZO ( $\Omega$ )	IREF ( $\Omega$ )	RS ( $\Omega$ )	RP ( $\Omega$ )	L (inches)	CL (pF)
100	475	33	49.9	5	2
85	412	27	42.2 or 43.2	5	2

## General SMBus Serial Interface Information

### How to Write

- Controller (host) sends a start bit
- Controller (host) sends the write address
- IDT clock will **acknowledge**
- Controller (host) sends the beginning byte location = N
- IDT clock will **acknowledge**
- Controller (host) sends the byte count = X
- IDT clock will **acknowledge**
- Controller (host) starts sending Byte N through Byte N+X-1
- IDT clock will **acknowledge** each byte **one at a time**
- Controller (host) sends a stop bit

Index Block Write Operation		
Controller (Host)		IDT (Slave/Receiver)
T	starT bit	
Slave Address		
WR	WRite	
Beginning Byte = N		ACK
		ACK
Data Byte Count = X		ACK
Beginning Byte N		ACK
O	X Byte	O
O		O
O		O
Byte N + X - 1		O
		ACK
P	stoP bit	

### How to Read

- Controller (host) will send a start bit
- Controller (host) sends the write address
- IDT clock will **acknowledge**
- Controller (host) sends the beginning byte location = N
- IDT clock will **acknowledge**
- Controller (host) will send a separate start bit
- Controller (host) sends the read address
- IDT clock will **acknowledge**
- IDT clock will send the data byte count = X
- IDT clock sends Byte N+X-1
- IDT clock sends **Byte 0 through Byte X (if X<sub>(H)</sub> was written to Byte 8)**
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- Controller (host) will send a stop bit

Index Block Read Operation		
Controller (Host)		IDT (Slave/Receiver)
T	starT bit	
Slave Address		
WR	WRite	
Beginning Byte = N		ACK
		ACK
RT	Repeat starT	
Slave Address		
RD	ReaD	
		ACK
		Data Byte Count=X
ACK		Beginning Byte N
ACK		O
O	X Byte	O
O		O
O		O
Byte N + X - 1		O
		Byte N + X - 1
N	Not acknowledge	
P	stoP bit	

**SMBus Table: Frequency Select Register, Read/Write Address (Selectable)**

Byte 0	Pin #	Name	Control Function	Type	0	1	Default
Bit 7	—	PD_Mode	PD# drive mode	RW	Driven	Hi-Z	1
Bit 6	—	OE_Mode	OE#_Disable drive mode	RW	Driven	Hi-Z	1
Bit 5	Reserved						0
Bit 4	Reserved						X
Bit 3	—	MODE1	BYPASS#/PLL1	RW	See <a href="#">Operating Mode Readback table</a>		Latched
Bit 2	Reserved						1
Bit 1	—	MODE0	BYPASS#/PLL0	RW	See <a href="#">Operating Mode Readback table</a>		Latched
Bit 0	Reserved						1

**SMBus Table: Output Control Register**

Byte 1	Pin #	Name	Control Function	Type	0	1	Default
Bit 7	Reserved						1
Bit 6	22, 23	DIF_6	Output Enable	RW	Disable	Enable	1
Bit 5	19, 20	DIF_5	Output Enable	RW	Disable	Enable	1
Bit 4	Reserved						1
Bit 3	Reserved						1
Bit 2	9, 10	DIF_2	Output Enable	RW	Disable	Enable	1
Bit 1	6, 7	DIF_1	Output Enable	RW	Disable	Enable	1
Bit 0	Reserved						1

NOTE: The SMBus Output Enable Bit must be '1' and the respective OE pin must be active for the output to run.

**SMBus Table: OE Pin Control Register**

Byte 2	Pin #	Name	Control Function	Type	0	1	Default
Bit 7	Reserved						1
Bit 6	22, 23	DIF_6	DIF_6 Stoppable with OE6#	RW	Free-run	Stoppable	1
Bit 5	19, 20	DIF_5	DIF_5 Stoppable with OE5#	RW	Free-run	Stoppable	1
Bit 4	Reserved						1
Bit 3	Reserved						1
Bit 2	9, 10	DIF_2	DIF_2 Stoppable with OE2#	RW	Free-run	Stoppable	1
Bit 1	6, 7	DIF_1	DIF_1 Stoppable with OE1#	RW	Free-run	Stoppable	1
Bit 0	Reserved						1

NOTE: To change the default to be "Stoppable", see the 9DB434.

**SMBus Table: Reserved Register**

Byte 3	Pin #	Name	Control Function	Type	0	1	Default
Bit 7			Reserved				X
Bit 6			Reserved				X
Bit 5			Reserved				X
Bit 4			Reserved				X
Bit 3			Reserved				X
Bit 2			Reserved				X
Bit 1			Reserved				X
Bit 0			Reserved				X

**SMBus Table: Vendor & Revision ID Register**

Byte 4	Pin #	Name	Control Function	Type	0	1	Default
Bit 7	—	RID3	REVISION ID	R	—	—	0
Bit 6	—	RID2		R	—	—	0
Bit 5	—	RID1		R	—	—	0
Bit 4	—	RID0		R	—	—	0
Bit 3	—	VID3	VENDOR ID	R	—	—	0
Bit 2	—	VID2		R	—	—	0
Bit 1	—	VID1		R	—	—	0
Bit 0	—	VID0		R	—	—	1

**SMBus Table: Device ID Register**

Byte 5	Pin #	Name	Control Function	Type	0	1	Default
Bit 7	—	DID7	Device ID 7 (MSB)	RW	Device ID is 46 Hex for 9DB436		0
Bit 6	—	DID6	Device ID 6	RW			1
Bit 5	—	DID5	Device ID 5	RW			0
Bit 4	—	DID4	Device ID 4	RW			0
Bit 3	—	DID3	Device ID 3	RW			0
Bit 2	—	DID2	Device ID 2	RW			1
Bit 1	—	DID1	Device ID 1	RW			1
Bit 0	—	DID0	Device ID 0	RW			0

**SMBus Table: Byte Count Register**

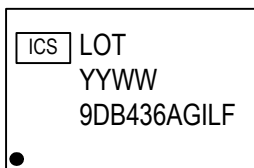
Byte 6	Pin #	Name	Control Function	Type	0	1	Default
Bit 7	—	BC7	Writing to this register configures how many bytes will be read back.	RW	—	—	0
Bit 6	—	BC6		RW	—	—	0
Bit 5	—	BC5		RW	—	—	0
Bit 4	—	BC4		RW	—	—	0
Bit 3	—	BC3		RW	—	—	0
Bit 2	—	BC2		RW	—	—	1
Bit 1	—	BC1		RW	—	—	1
Bit 0	—	BC0		RW	—	—	1

## Package Outline Drawings

The package outline drawings are appended at the end of this document and are accessible from the link below. The package information is the most current data available.

[www.idt.com/document/psc/28-tssop-package-outline-drawing-44-mm-body-065mm-pitch-pgg28d1](http://www.idt.com/document/psc/28-tssop-package-outline-drawing-44-mm-body-065mm-pitch-pgg28d1)

## Marking Diagram



- “LOT” denotes the lot number.
- “YYWW” is the last two digits of the year and the work week number when the part was assembled.
- Line 3: Part number.

## Ordering Information

Orderable Part Number	Package	Carrier Type	Temperature
9DB436AGILF	4.4mm body, 0.65mm pitch 28-TSSOP	Tubes	-40° to +85°C
9DB436AGILFT	4.4mm body, 0.65mm pitch 28-TSSOP	Tape and Reel	-40° to +85°C

“LF” suffix to the part numbers are the Pb-Free configuration and are RoHS compliant.

“A” is the device revision designator.

## Revision History

Revision Date	Description of Change
October 12, 2018	Initial release.



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