Description
The IDT SGAS701 is a solid-state chemiresistor sensor designed to detect hydrogen in air. The sensor uses an integrated heater with highly sensitive MOx material tailored for detection of hydrogen.

The chemiresistor sensors of IDT’s SGAS family are based upon the principle that metal oxide materials undergo surface interactions (physisorption and chemisorption) with gas molecules at elevated temperatures, resulting in a measurable change in electrical resistance. As these materials are polycrystalline (i.e., composed of multiple grains with distinct grain boundaries), the adsorbed gases have significant electronic effects on the individual grains. These gas-solid interactions result in a change in electron (or hole) density at the surface (i.e., a space charge forms), which in turn changes the electrical conductivity of the oxide. IDT has developed a set of nanostructured gas sensing materials with excellent sensitivity and stability.

Features
- High sensitivity to low hydrogen concentrations (<10 to 1000 ppm)
- Fast response time (<15 seconds at 100 ppm)
- Environmental temperature range of -20°C to 50°C
- Environmental humidity range of 0% to 90% RH, noncondensing
- Low dependence on flow rate
- Rugged, reliable sensor based on IDT’s exclusive technology

Typical Applications
- Leak Detection
- Gas Concentration Detection
- Breath Detection

Available Support
- Evaluation Kit – SMOD701KITV1
- Application Notes
- Instruction Videos
- Reference Design
Contents
1. Pin Assignments .................................................................................................................. 4
2. Pin Descriptions .................................................................................................................. 4
3. Sensor Specifications ........................................................................................................... 4
4. Sensor Characteristics ......................................................................................................... 5
5. Basic Measurement Circuit ................................................................................................. 6
6. Heater Driver Circuits and Control ....................................................................................... 7
   6.1 Constant Voltage Drive .................................................................................................. 7
   6.2 Constant Current Drive .................................................................................................. 8
   6.3 Pulse-Width Modulation ............................................................................................... 8
   6.4 Operating the Sensor at Temperature Extremes ............................................................. 9
7. Sensing Characteristics ....................................................................................................... 10
   7.1 Sensitivity .................................................................................................................... 10
   7.2 Response and Recovery Time ...................................................................................... 12
   7.3 Cross-Sensitivity .......................................................................................................... 13
8. Maximum ESD Ratings ....................................................................................................... 14
9. Mechanical Stress Testing .................................................................................................. 14
10. Package Drawing and Dimensions .................................................................................... 15
11. Applications and Use Conditions ...................................................................................... 16
12. Ordering Information ......................................................................................................... 16
13. Revision History ................................................................................................................. 16

List of Figures
Figure 1. Product Photo ........................................................................................................... 1
Figure 2. Pin Assignments for SGAS701 – Top View ............................................................... 4
Figure 3. Typical Sensor Response Characteristic ................................................................. 6
Figure 4. Basic Measurement Circuit ..................................................................................... 6
Figure 5. Three-Terminal Voltage Regulator ........................................................................ 7
Figure 6. Voltage-Controlled Constant Current Circuit ........................................................ 8
Figure 7. Recommended Applied Heater Voltage as a Function of Environmental Temperature ........................................... 9
Figure 8. Typical Sensor Response to a Range of Hydrogen Concentrations in a Background of 30% RH at Room Temperature ........................................... 10
Figure 9. Typical Sensor Sensitivity to a Range of Hydrogen Concentrations in a Background of 30% RH at Room Temperature ........................................... 11
Figure 10. Typical Sensor Response to Step Changes in Hydrogen Concentration for Four SGAS701 Sensors ................................................................. 12
Figure 11. Typical Sensor Response to other Common Gases ................................................ 13
Figure 12. TO-39 Package (TO4) Outline Drawing PSC-4676 .................................................. 15
List of Tables

Table 1. Pin Descriptions ...........................................................................................................4
Table 2. Electrical Specifications ...............................................................................................4
Table 3. Temperature Specifications ..........................................................................................5
Table 4. Maximum ESD Ratings .................................................................................................14
Table 5. Mechanical Stress Test Conditions ...............................................................................14
1. Pin Assignments

Figure 2. Pin Assignments for SGAS701 – Top View

2. Pin Descriptions

Table 1. Pin Descriptions

<table>
<thead>
<tr>
<th>Pin Number</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Heater +</td>
<td>Positive input for (V_H) heater voltage supply</td>
</tr>
<tr>
<td>2</td>
<td>Sensor +</td>
<td>High-side of resistive sensor element; positive input for sensing voltage (V_C)</td>
</tr>
<tr>
<td>3</td>
<td>Heater −</td>
<td>Negative (ground) input for (V_H) heater voltage supply</td>
</tr>
<tr>
<td>4</td>
<td>Sensor −</td>
<td>Low-side of resistive sensor element; connects to middle of resistor divider circuit to produce sensing voltage output ((V_{OUT}))</td>
</tr>
</tbody>
</table>

3. Sensor Specifications

Note: All measurements were made in dry gas at room temperature. Specifications are subject to change.

Table 2. Electrical Specifications

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Conditions</th>
<th>Minimum</th>
<th>Typical</th>
<th>Maximum</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>(P_H)</td>
<td>Heater power consumption</td>
<td>(V_H = 5.4) V</td>
<td>600</td>
<td>600</td>
<td>600</td>
<td>mW</td>
</tr>
<tr>
<td>(V_H)</td>
<td>Recommended heater voltage</td>
<td>(T_{SENSOR} = 240°C)</td>
<td>5.4</td>
<td>5.4</td>
<td>5.4</td>
<td>VDC</td>
</tr>
<tr>
<td>(R_H)</td>
<td>Heater resistance</td>
<td>At room temperature</td>
<td>28</td>
<td>30</td>
<td>32</td>
<td>Ω</td>
</tr>
<tr>
<td>(V_C)</td>
<td>Recommended sensing voltage</td>
<td></td>
<td>2.5</td>
<td>2.5</td>
<td>2.5</td>
<td>VDC</td>
</tr>
<tr>
<td>(R_{10})</td>
<td>Resistance in 10ppm (H_2)</td>
<td></td>
<td>30</td>
<td>30</td>
<td>30</td>
<td>kΩ</td>
</tr>
<tr>
<td>(R_{100})</td>
<td>Resistance in 100ppm (H_2)</td>
<td></td>
<td>10</td>
<td>10</td>
<td>10</td>
<td>kΩ</td>
</tr>
<tr>
<td>(R_{50} / R_{100})</td>
<td>Resolution: Resistance in 50 ppm / Resistance in 100 ppm</td>
<td>&gt; 1.2</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Table 3. Temperature Specifications

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Conditions</th>
<th>Minimum</th>
<th>Typical</th>
<th>Maximum</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>T_{OP}</td>
<td>Sensor Operation Temperature</td>
<td>V_{IH} = 5.4V</td>
<td>240</td>
<td></td>
<td></td>
<td>°C</td>
</tr>
<tr>
<td>T_{AMB}</td>
<td>Recommended Environmental Temperature Range</td>
<td></td>
<td></td>
<td>-20</td>
<td>50</td>
<td>°C</td>
</tr>
<tr>
<td>T_{STOR}</td>
<td>Maximum Storage Temperature Range</td>
<td></td>
<td></td>
<td>-50</td>
<td>125</td>
<td>°C</td>
</tr>
</tbody>
</table>

The sensor is not intended for continuous operation above or below the environmental temperature specification, but exposure for short durations will not will not harm the sensor.

4. Sensor Characteristics

IDT’s solid-state chemiresistive sensors are an advanced type of gas-sensitive resistor; i.e. they sense the presence of a target gas through a change in resistance of the sensing element. Most sensors exhibit reduced resistance as gas concentration increases, typically over several orders of magnitude across the sensing range.

Solid-state chemiresistive sensors show a reduced resistance with increasing gas concentration according to Equation 1:

\[ R_S = A \cdot C^\alpha \]  

Equation 1

where \( R_S \) is resistance, \( C \) is concentration, and \( A \) and \( \alpha \) are constants. Although several refined versions of this equation are available for specific sensors or sensing materials, the fundamental resistance versus concentration relationship for all of IDT’s n-type sensors follows Equation 1. Taking the log of both sides of the equation results in Equation 2:

\[ \log(R_S) = \log(A) - \alpha \cdot \log(C) \]  

Equation 2

This shows that log resistance versus log concentration is linear.

An immediately observable consequence of Equation 1 is that sensor resistance will change rapidly at low concentrations and much less at high concentrations. This is illustrated in the following example:

\[ R_{GAS,10ppm} = 20k\Omega \]
\[ R_{GAS,100ppm} = 5k\Omega \]
\[ A_{GAS} = 8.0 \times 10^4 \]
\[ \alpha_{air} = 0.602 \]

The non-logarithmic response plot shown in Figure 3 illustrates the fundamental challenge that must be addressed when measuring the resistance of chemiresistor sensors and relating these measurements to gas concentrations. Additional nonlinear effects from the measurement circuitry exacerbate these challenges and must be understood in order to account for or eliminate these effects.
The electronic instrumentation used to detect this change in resistance influences the quality and accuracy of the gas sensing result. In particular, the choice of the analog front-end used to measure resistance can ultimately have a significant effect on overall measurement characteristics and must be selected with care. For additional information, see IDT's Application Note – Resistance Measuring Circuits for SGAS Sensors.

5. Basic Measurement Circuit

The sensor can be operated using a simple voltage divider. This requires two voltage supplies: the heater voltage (V_H) and circuit voltage (V_C). V_H is applied to the heater in order to maintain a constant, elevated temperature for optimum sensing. V_C is applied to allow a measurement of the output voltage (V_OUT) across a load resistor (R_L).

Pins 1 and 3 are attached to the heater. Apply V_H across these pins. Pins 2 and 4 are attached to the resistive sensor element. Connect these pins in the measurement circuit. IDT supplies basic measurement circuitry for many of our sensors. More information can be found in IDT’s Application Note – Resistance Measuring Circuits for SGAS Sensors.
6. Heater Driver Circuits and Control

The SGAS701 sensor contains a resistive element that is used to heat the sensor to the target operating temperature as shown in Table 3. The SGAS701 sensor uses a thermistor heater element with a positive temperature coefficient, i.e. the heater resistance increases from the cold (room temperature) resistance as power is applied. This provides the opportunity for constant power and constant resistance (closely related to constant temperature) control of the heater.

6.1 Constant Voltage Drive

The simplest method of applying heater power is the use of a constant voltage drive. Because heaters draw a relatively large amount of current in normal operation, a method of current amplification is required. Additionally, because relatively small changes in voltage levels will affect the temperature of the heater (and consequently gas sensitivity), voltage regulation is required.

An easily implemented control circuit utilizes a three-terminal voltage regulator, with the LM317 serving as an example as shown in Figure 5.

**Figure 5. Three-Terminal Voltage Regulator**

![Three-Terminal Voltage Regulator Diagram](image)

\[ V_{\text{HEATER}} = 1.25V \times (1 + R2/R1) + I_{\text{ADJ}} \times R2 \]

R1 and R2 (one of these can be a potentiometer) are selected to provide the target heater drive voltage for the sensor. The example using the LM317 is capable of regulating voltages down to 1.25V and is thus suitable for SGAS701 sensors. However, a wide variety of more advanced three-terminal voltage regulators is available from component manufacturers.

Constant voltage circuits of this type are relatively efficient, particularly if a switching regulator is used. Adding external control of the regulator output voltage with a current sensing resistor would allow feedback control of the sensor heater power and temperature, but the required circuitry is somewhat complex. Applications requiring feedback control are better implemented with the constant current circuit that is described in section 6.2.
6.2 Constant Current Drive

The constant current drive is more complex and costly than the constant voltage drive, but the added capabilities justify the expense for many applications. Additionally, the circuit is "microcontroller friendly" because the heater current is directly controllable via an input voltage signal, and feedback control of the heater is possible through a simple measurement of the resultant voltage on the heater.

The constant current heater drive circuit is shown in Figure 6. $V_{\text{IN}}$ (supplied by an external source) is forced across $R_1$, thus providing a predictable current through both $R_1$ and $R_2$, with a predictable voltage drop (relative to $V_{\text{DD}}$) across $R_2$. An equivalent drop is imposed across $R_3$, and current through both $R_3$ and $R_{\text{HEATER}}$ is thus controlled independently of the load resistance according to the equation in Figure 6.

The heater current is controllable to below 1mA. However, the circuit is inefficient compared to others, as power is dissipated in $R_3$ and $Q_2$ as well as the heater. Limiting the supply voltage to several hundred mV above the highest required drive voltage will help increase circuit efficiency.

While $V_{\text{IN}}$ can be supplied by a fixed voltage reference (such as a divider), the flexibility of the circuit is most revealed when $V_{\text{IN}}$ is supplied by a microcontroller via a digital-to-analog converter (DAC). With this type of control, the heater drive can be time-programmed to allow pulsing of the heater with variable amplitude. Determination of the heater power or resistance is possible by reading the voltage level at the heater. Since the heater temperature directly correlates with heater resistance, direct feedback control of bulk heater temperature is possible by raising or lowering the heater current such that $(V_{\text{HEATER}}/I_{\text{HEATER}})$ is constant. Likewise, constant heater power can be maintained by controlling current to keep $(V_{\text{HEATER}} \ast I_{\text{HEATER}})$ constant.

**Figure 6. Voltage-Controlled Constant Current Circuit**

```
\[
i_{\text{HEATER}} = V_{\text{IN}} \ast R_2 / (R_1 \ast R_3)
\]
```

6.3 Pulse-Width Modulation

Pulse-width modulation (PWM) is a very efficient method of providing controllable drive to the heater. However, this method has not undergone sufficient testing at IDT to allow IDT to recommend it for any sensors in the SGAS family.

PWM heater drive design should keep the following in mind:

- Voltage to the heater should not exceed the maximum voltage allowed for a given heater family.
- A low-pass filter should be considered as part of the sensor signal circuit path to reduce noise from the heater PWM.
6.4 Operating the Sensor at Temperature Extremes

When this sensor is used outdoors, the relative response of the sensor to the target gases will be a function of environmental temperature when the sensor is operated with a constant voltage or current applied to the heater. This behavior is readily explained by considering that large shifts in ambient temperatures affect the operating temperature at the sensor surface, in turn altering the kinetics and thermodynamics of the interaction of the sensing surface with flammable gases. This alters the electrical conduction of the sensor element (the basis of metal-oxide sensor operation). Recommendation: In these cases, operate the sensor in a feedback loop, where constant resistance at the heater is maintained. For operation in ambient conditions above $T_{\text{AMB}} = 50^\circ\text{C}$, additional compensation of the sensor signal may be required and should be developed by the user with the specific application and operating conditions in mind. A graphical representation of the recommended temperature set-point voltage versus environmental temperature is shown in Figure 7.

The mathematical description for the curve is given in Equation 3:

$$V_H = -0.01 \times \text{Environmental Temperature} \, [^\circ\text{C}] + 5.5$$

Equation 3

**Figure 7. Recommended Applied Heater Voltage as a Function of Environmental Temperature**
7. Sensing Characteristics

The following graphs show the typical responses that are to be expected from the sensors on exposure to a variety of test conditions. For SGAS701 sensor specifications, refer to Table 4.

7.1 Sensitivity

The typical response and sensitivity of the SGAS701 sensor to hydrogen is shown in Figure 8 and Figure 9. Sensitivity is defined as the ratio between the resistance in air ($R_{\text{Air}}$) and the resistance in gas ($R_{\text{Gas}}$).

Figure 8. Typical Sensor Response to a Range of Hydrogen Concentrations in a Background of 30% RH at Room Temperature
Figure 9. Typical Sensor Sensitivity to a Range of Hydrogen Concentrations in a Background of 30% RH at Room Temperature
7.2 Response and Recovery Time

The typical response and recovery time of a sampling of seven SGAS701 sensors is shown in Figure 10. The response and recovery time can be strongly affected by the sensor location within the system, including any barriers to diffusion of gas to and from the sensor surface, and whether the sensor is operated with or without a pump or other source of external flow.

Figure 10. Typical Sensor Response to Step Changes in Hydrogen Concentration for Four SGAS701 Sensors
7.3 Cross-Sensitivity

The response of the SGAS701 sensors to a range of other common gases is shown in Figure 11.

**Figure 11. Typical Sensor Response to other Common Gases**
8. Maximum ESD Ratings

Table 4. Maximum ESD Ratings

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Conditions</th>
<th>Minimum</th>
<th>Maximum</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{HBM1}$</td>
<td>Electrostatic Discharge Tolerance – Human Body Model (HBM1)</td>
<td></td>
<td>2000</td>
<td>–</td>
<td>V</td>
</tr>
<tr>
<td>$V_{CDM}$</td>
<td>Electrostatic Discharge Tolerance – Charged Device Model (CDM) on Packaged Module</td>
<td></td>
<td>500</td>
<td>–</td>
<td>V</td>
</tr>
</tbody>
</table>

9. Mechanical Stress Testing

The qualification of the SGAS701 is based on the JEDEC standard (JESD47).

After subjection to the mechanical shock and vibration testing conditions given in Table 5 the SGAS701 sensor will meet the specifications given in this document. For information on constant acceleration test conditions and limits, contact IDT (see contact information on last page).

Table 5. Mechanical Stress Test Conditions

<table>
<thead>
<tr>
<th>Stress Test</th>
<th>Standard</th>
<th>Conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mechanical Shock</td>
<td>JESD22-B104, M2002</td>
<td>Y1 plane only, 5 pulses, 0.5 ms duration, 1500 g peak acceleration</td>
</tr>
<tr>
<td>Vibration Variable Frequency</td>
<td>JESD22-B103, M2007</td>
<td>20Hz to 2kHz (log variation) in &gt; 4 minutes, 4 times in each orientation, 50g peak acceleration</td>
</tr>
</tbody>
</table>
10. Package Drawing and Dimensions

Figure 12. TO-39 Package (TO4) Outline Drawing PSC-4676
11. Applications and Use Conditions

The SGAS701 sensor is designed for gas leak detection and measurement of ppm levels of hydrogen. The sensor is not intended, recommended, or approved for use in safety or life protecting applications or in potentially explosive environments. IDT disclaims all liability for such use.

12. Ordering Information

<table>
<thead>
<tr>
<th>Orderable Part Number</th>
<th>Package</th>
<th>MSL Rating</th>
<th>Shipping Packaging</th>
<th>Temperature</th>
</tr>
</thead>
<tbody>
<tr>
<td>SGAS701</td>
<td>4-pin TO-39 (TO4)</td>
<td>1</td>
<td>Tray</td>
<td>-20°C to 50°C</td>
</tr>
<tr>
<td>SMOD701KITV1</td>
<td>SMOD701 Evaluation Kit, including the SMOD701 Smart Sensing Module (includes the SGAS701 sensor), mini-USB cable, and wall-mounted 9V power supply. The SMOD7xx Application Software is available for download at <a href="http://www.idt.com/SMOD701">www.idt.com/SMOD701</a>.</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

13. Revision History

<table>
<thead>
<tr>
<th>Revision Date</th>
<th>Description of Change</th>
</tr>
</thead>
<tbody>
<tr>
<td>November 16, 2016</td>
<td>Minor correction.</td>
</tr>
<tr>
<td>October 25, 2017</td>
<td>Full revision.</td>
</tr>
<tr>
<td>November 9, 2016</td>
<td>Initial release with IDT branding.</td>
</tr>
</tbody>
</table>
Notice

1. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation or any other use of the circuits, software, and information in the design of your product or system. Renesas Electronics disclaims any and all liability for any losses and damages incurred by you or third parties arising from the use of these circuits, software, or information.

2. Renesas Electronics hereby expressly disclaims any warranties against and liability for infringement or any other claims involving patents, copyrights, or other intellectual property rights of third parties, by or arising from the use of Renesas Electronics products or technical information described in this document, including but not limited to, the product data, drawings, charts, programs, algorithms, and application examples.

3. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.

4. You shall not alter, modify, copy, or reverse engineer any Renesas Electronics product, whether in whole or in part. Renesas Electronics disclaims any and all liability for any losses or damages incurred by you or third parties arising from such alteration, modification, copying or reverse engineering.

5. Renesas Electronics products are classified according to the following two quality grades: "Standard" and "High Quality". The intended applications for each Renesas Electronics product depends on the product's quality grade, as indicated below.

   *Standard": Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; industrial robots; etc.

   *High Quality": Transportation equipment (automobiles, trains, ships, etc.); traffic control (traffic lights); large-scale communication equipment; key financial terminal systems; safety control equipment; etc.

Unless expressly designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not intended or authorized for use in products or systems that may pose a direct threat to human life or bodily injury (artificial life support devices or systems; surgical implantations; etc.), or may cause serious property damage (space systems; undersea repeaters; nuclear power control systems; aircraft control systems; key plant systems; military equipment; etc.). Renesas Electronics disclaims any and all liability for any damages or losses incurred by you or any third parties arising from the use of any Renesas Electronics product that is inconsistent with any Renesas Electronics data sheet, user’s manual or other Renesas Electronics document.

6. When using Renesas Electronics products, refer to the latest product information (data sheets, user's manuals, application notes, "General Notes for Handling and Using Semiconductor Devices" in the reliability handbook, etc.), and ensure that usage conditions are within the ranges specified by Renesas Electronics with respect to maximum ratings, operating power supply voltage range, heat dissipation characteristics, installation, etc. Renesas Electronics disclaims any and all liability for any malfunctions, failure or accident arising out of the use of Renesas Electronics products outside of such specified ranges.

7. Although Renesas Electronics endeavors to improve the quality and reliability of Renesas Electronics products, semiconductor products have specific characteristics, such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Unless designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not subject to radiation resistance design. You are responsible for implementing safety measures to guard against the possibility of bodily injury, injury or damage caused by fire, and/or danger to the public in the event of a failure or malfunction of Renesas Electronics products, such as safety design for hardware and software, including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult and impractical, you are responsible for evaluating the safety of the final products or systems manufactured by you.

8. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. You are responsible for carefully and sufficiently investigating applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive, and using Renesas Electronics products in compliance with all applicable laws and regulations. Renesas Electronics disclaims any and all liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.

9. Renesas Electronics products and technologies shall not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations. You shall comply with any applicable export control laws and regulations promulgated and administered by the governments of any countries asserting jurisdiction over the parties or transactions.

10. It is the responsibility of the buyer or distributor of Renesas Electronics products, or any other party who distributes, disposes of, or otherwise sells or transfers the product to a third party, to notify such third party in advance of the contents and conditions set forth in this document.

11. This document shall not be reprinted, reproduced or duplicated in any form, in whole or in part, without prior written consent of Renesas Electronics.

12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products.

(Note1) "Renesas Electronics" as used in this document means Renesas Electronics Corporation and also includes its directly or indirectly controlled subsidiaries.

(Note2) "Renesas Electronics product(s)" means any product developed or manufactured by or for Renesas Electronics.

(Rev.4.0-1 November 2017)

Corporate Headquarters
TOYOSU FORESIA, 3-2-24 Toyosu,
Koto-ku, Tokyo 135-0061, Japan
www.renesas.com

Contact Information
For further information on a product, technology, the most up-to-date version of a document, or your nearest sales office, please visit:
www.IDT.com/go/support

Trademarks
Renesas and the Renesas logo are trademarks of Renesas Electronics Corporation. All trademarks and registered trademarks are the property of their respective owners.

© 2019 Renesas Electronics Corporation. All rights reserved.